

# Performance Analysis of On Demand Routing Protocols in Vehicular Ad Hoc Network (VANET)

May Zar Win, Khin Khat Khat Kyaw, Cho Cho Myint

**Abstract**—Vehicular ad-hoc network (VANET) is an intelligent network technology in wireless communication where the vehicles act as a mobile nodes to share data without any central point for a safety issue. VANET protocols are important for road-safety, traffic efficiency and management applications. In city, vehicles are very crowded in roads. When VANET communication on city map is performed, routing overhead is an essential point to reduce in VANET. Among the current routing protocols, reactive routing protocols are favoured in mobile ad-hoc network (MANET) because they help in reducing overheads by continuously sending the data for better communication. In order to design a suitable and efficient routing protocol in VANET, a comprehensive study on popular existing VANET routing protocols must be considered as a tangible need. In this paper AODV, AOMDV and DSR routing protocols on real traffic environments are tested and analyzed the packet delivery ratio, end-to-end delay, throughput and routing overhead of VANET. The Simulation studies are analyzed using NS2.

**Index Terms**—VANET, MANET, AODV, AOMDV, DSR, NS2.

## 1) INTRODUCTION

Vehicular Ad-Hoc Networks (VANETs) are special type of Mobile ad Hoc Networks (MANETs), where wireless-equipped vehicles form a network spontaneously while traveling along the road. VANET is uniquely differentiated based on two special & unique characteristics of wireless networks such as high dynamic connectivity in network and frequently change of network topology. These two properties separate the VANET from other networks such as MANET etc. the increased utilization of vehicles on roads, also increases the road accidents, unsafe journeys and polluted environment etc. and these things motivated us to initiate this work. To assure the safe journey of passengers, drivers and provide the comfortable and easy driving environment, different messages for different requirement are communicated to nearby vehicles called the inter-vehicle communications. Vehicular network have two main types of communications. One main type of communication is vehicle

to vehicle or on-board unit (OBU) V2V and second is Vehicle to infrastructure or Road Side Unit (RSU) V2I communication as shown in Figure 1.

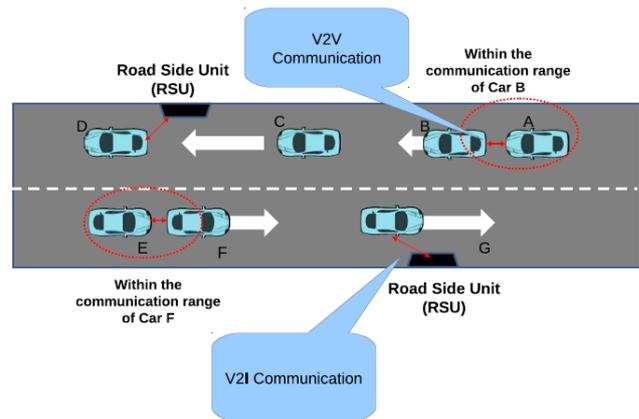


Figure 1. Vehicular Adhoc Network (V2V and V2I)

There are many routing protocols for ad hoc networks [1], [2], [3]. Here we are considering AODV, AOMDV and DSR routing protocol based on two parameters: vehicle velocity and vehicle density. Ad Hoc On-Demand Distance Vector (AODV) is one of the promising available reactive routing algorithms. AODV is an on demand routing protocol. This protocol finds routes for a node only when it has data packet for transmission. AODV routing consists of three phases: route discovery, data transmission and route maintenance. Ad Hoc On-Demand Multipath Distance Vector (AOMDV) [4] routing protocol is an extension to the AODV protocol for computing multiple loop-free and link disjoint paths. The Dynamic Source Routing (DSR) protocol is based on secure routing method. In this algorithm the mobile node whose want to send data in network knows the complete path of destination and store that in route cache. The contents are organized as follows. The next section is a brief of Related Work and section 3 discusses about the overview of AODV, AOMDV and DSR routing protocol. Finally, the simulation results and conclusion are presented in section 4 and section 5.

## 2) RELATED WORKS

Several research studies have been carried out to enhance the routing on VANET. The performance analysis of the protocols is the major step before selecting a particular routing protocol. In fact, path routing and protocol selection are the primary strategies to design any vehicular ad-hoc

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network considering data delivery, data integrity and especially time delivery.

Routing in VANET can be proactive, reactive and hybrid. Reactive schemes maintain routes to the nodes only when required, which reduces the routing overhead. A proactive routing scheme periodically finds the routes to all of the nodes within the network, which causes an increase in routing overhead [4]. Link state routing algorithms are usually used by proactive schemes. The delay encountered, when the packet needs to be sent to a particular node, is less for the proactive schemes as compared to the reactive schemes. However, the routing overhead of the proactive schemes are more as compared to reactive schemes. Moreover, the convergence time for proactive schemes is high as compared to the reactive schemes. Therefore, the efficiency of the proactive scheme decreases for a network where the topology changes frequently. A hybrid routing scheme - Zone Routing Protocol (ZRP) [5] combines the features of both the proactive and reactive schemes.

In [6], authors illustrate the differences between AODV, DSR and DSDV based on TCP and CBR connection with various network parameters. The performance of these three routing protocols shows some differences in low and high node density. Indeed, in low density with low pause time, the PDR of CBR connection for these routing protocols is low. While for TCP connection, the PDR is high for DSR and average for DSDV.

In [7], DSR is a reactive routing protocol in which the primary aspect is to store the whole path from source to destination in the routing table instead of having the next hop stored (AODV routing protocol). Therefore, the packet header must include all nodes through which the packet must travel to be delivered to the destination. Similar to AODV, the RREQ and RREP are used to perform the route discovery and delivering the reply message back to the source. DSDV is a proactive routing protocol which maintains the route to the destination before it is required to be established. Nodes exchange their routing tables periodically or when it is required to be exchanged.

### 3) ROUTING PROTOCOLS IN VANET

Many routing protocols have been developed for VANETs, which are classified in the literature [8],[9] in different ways and according to many aspects. On Demand routing protocols work on the principle of creating routes as and when required between a source and destination node pair in a network topology. Our discussion is limited to three on-demand ad-hoc routing protocols AODV, AOMDV and DSR, as follows.

#### 1) Ad-hoc On-demand Distance Vector (AODV)

AODV is a famous on-demand routing protocol for ad hoc network, which consists of route discovery and route maintenance processes. It uses three kinds control messages: Route Request (RREQ), Route Reply (RREP) and Route Error (RERR) [10].

When a source node wants to send data packets to destination, it needs to look for available routing information in route table. If no available route exists, route discovery is initiated. To handle this process, the source node broadcasts a route request (RREQ) for the destination. An intermediate node receiving RREQ first sets up a reverse route to the

source node if needed, then rebroadcasts the RREQ. If an intermediate node is the destination or has a "newer" route to the destination, it may generate a RREP. When the RREP routes back to the source via the reverse path established previously, a forward path to the destination can be established by intermediate nodes based on the information carried by RREP. When the RREP arrives at the source, a route between the source and destination is built up. The source node uses expanding ring search when discovering new routes to limit flooding of the network wide and reduce the overhead.

In AODV, hello message, local repair, RREQ and RERR packet are used in route maintenance process. Nodes in the active routes periodically broadcast hello message to their neighbors to announce the connectedness. Its neighbors update their route table according to the information carried by hello message. If a node doesn't receive hello message within fixed intervals, the corresponding node is considered to be unreachable, and this node initiates local repair mechanism by broadcasting RREQ downstream if its location is rather close to the destination. During local repair process, the initial node buffers data packets until receiving the corresponding RREP which means new route is reconstructed. However, if local repair is unsuccessful, this node sends RERR packet to the source node. As a result, the source node will try to reestablish a new route discovery process, and intermediate nodes may detect the link break.

#### 2) Ad-hoc On-demand Multipath Distance Vector Routing (AOMDV)

Ad hoc On-demand Multipath Distance Vector (AOMDV) [11, 12] is an extension to the AODV protocol for computing multiple loop-free and link-disjoint paths. AOMDV is a reactive hop-by-hop routing protocol which finds node/link-disjoint multiple paths. In AOMDV when a source has packets to send to a destination and finds no routes in its routing table, it invokes a route discovery by broadcasting RREQ packets. Route discovery in AOMDV is similar to AODV. A RREQ packet in AOMDV includes all fields as that in AODV. Besides, it includes an additional field called the last hop, i.e., the neighboring node of the source. This information and the next-hop information, i.e., the node from which to receive the RREQ, are used to achieve link-disjointness for reverse paths to the source. A node may receive multiple duplicate RREQ packets. For each packets received, it examines if an alternate reverse path to the source can be formed such that loop-freedom and link-disjointness are preserved. In an attempt to get multiple link-disjoint routes, the destination replies to duplicate RREQs, the destination only replies to RREQs arriving via unique neighbors. After the first hop, the RREPs follow the reverse paths, which are node disjoint and thus link-disjoint. The trajectories of each RREP may intersect at an intermediate node, but each takes a different reverse path to the source to ensure link disjointness. The advantage of using AOMDV is that it allows intermediate nodes to reply to RREQs, while still selecting disjoint paths. But, AOMDV has more message overheads during route discovery due to increased flooding and since it is a multipath routing protocol, the destination replies to the multiple RREQs those results are in longer overhead.



Parameters	Values
Network Simulator	NS2.35
Traffic Simulator	SUMO
Map Model	OSM (Yangon City)
Antenna Type	Omni Antenna
Routing Protocol	AODV,AOMDV, DSR
Simulation Time	200s
Number of Nodes	50, 100, 150,200
Number of connections	10, 20, 30, 40 TCP connections
Packet size	512 bytes

### 3) Network Performance Indicators

In order to analyze the simulation results, the following performance indicators were utilized in our study:

- Packet Delivery Ratio: the ratio between the number of packets received by the destination and the number of packets sent by the source.
- End-to-End Delay: the time taken for a packet to be transmitted across a network from source to destination.
- Throughput: refers to the number of packets successfully transmitted from source to destination. It has an important consideration in selecting a routing protocol for mobile networks.
- Routing Overhead: The number of control packets transmitted, with each hop-wise transmission of a control packet counted as one transmission.

### 4) Simulation Results

The simulation is aimed to analyze the impact of increasing the size of network on each Packet Delivery Ratio, End-to-End Delay, Throughput and Routing Overhead on different routing protocols (AODV, AOMDV, DSR) VANET environment using NS2 simulator. Two kinds of variable are considered in our simulation including the number of nodes (vehicles) and the number of simultaneous connections with various speeds of nodes.

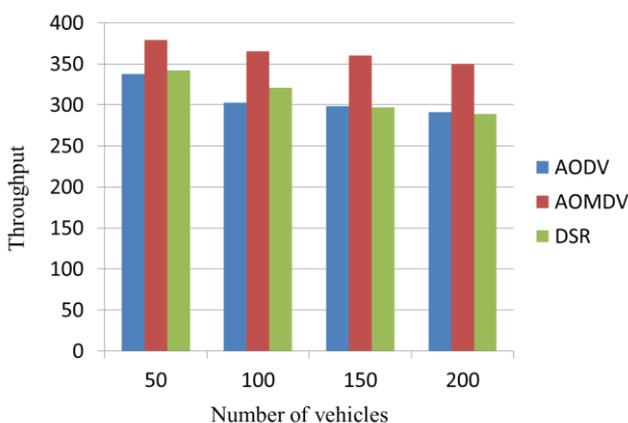


Figure 4: Throughput of AODV, AOMDV, DSR protocols

Figure 4 shows the throughput of our simulation of routing protocols. It indicates that AOMDV has best throughput and AODV and DSR have lower throughput than AOMDV. In the simulation of figure 4 and figure 5, the number of tcp connections is fixed to 10 simultaneous connections.

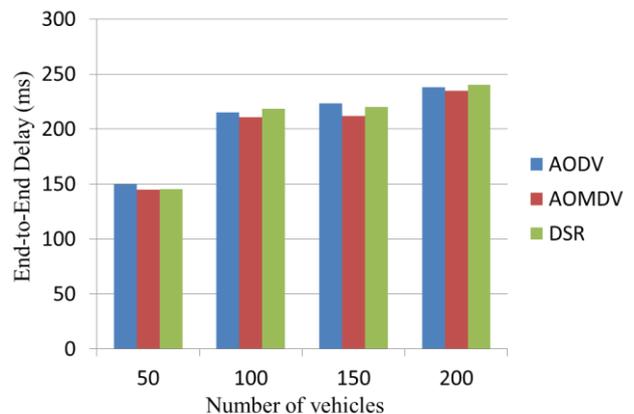


Figure 5: End-to-End Delay of AODV, AOMDV, DSR protocols

Figure 5 shows the delay time of our simulation of routing protocols. It indicates that AOMDV has lower delay than AODV and DSR. Indeed, switching directly to another alternative route gives in some cases some advantages than waiting for adjacent nodes to relay undelivered unicast packets. AODV and DSR slightly higher delay than AOMDV.

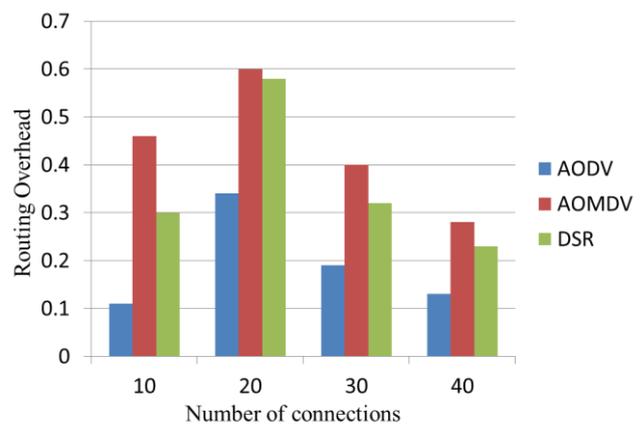


Figure 6: Routing Overhead of AODV, AOMDV, DSR protocols

Figure 6 shows the routing overhead of AODV, AOMDV, DSR protocols. It indicates AOMDV generates more routing overhead due to its multipath conception and maintenance than AODV and DSR. But AODV has best routing overhead value. In the simulation of figure 6 and figure7, the number of vehicles is fixed to 50 vehicles.

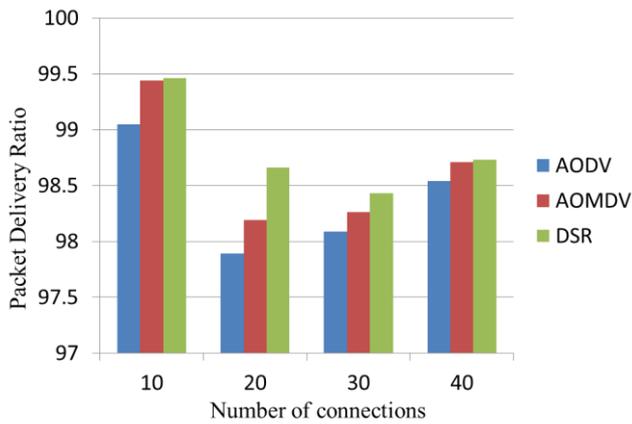


Figure 7: Packet Delivery Ratio of AODV, AOMDV, DSR protocols

Figure 7 shows packet delivery ratio (PDR) of AODV, AOMDV and DSR protocols. When the number of connections increases, DSR has highest PDR value than AODV and AOMDV protocols.

#### 4) CONCLUSION

In summary, in this paper we analyze under realistic conditions different routing protocols namely AODV, AOMDV and DSR to evaluate their performance of answering the routing challenges in VANET context. Our results show that AOMDV gives better performance as compared to AODV and DSR in terms of throughput and end-to-end delay but worst in terms of routing overhead and packet delivery ratio. We have also seen that AODV routing protocol is best in terms of routing overhead and DSR routing protocol is best in terms of packet delivery ratio. Thus, we should take into account the connectivity problem caused by the various vehicles' velocity. Our task will be based on finding the relevant parameters that make us able to select the most reliable route during the route selection process.

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